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Name	Omar Yaseen Ismael				
Current academic rank	Asst. Professor				
Workplace	College of Electronics Engineering	Academic department	Systems and Control Engineering		
General specialization	Mechatronics Engineering	Specialization	Control Systems Engineering		
E-mail	omar.ismael@uoninevah.edu.iq				

Academic qualifications

Degree	University Name	Country Studied at	<u>.</u>	
Ph.D. Student	University of Technology	Iraq	Control Engineering	
M.Sc.	University of Newcastle Upon Tyne	United Kingdom	Mechatronics Engineering	2014
B.Sc.	University of Mosul	Iraq	Mechatronics Engineering	2010
Diploma	Northern Technical University	Iraq	Pharmacy Technician	2023

Academic rank:

Academic rank	Date of Obtaining the rank	Academic rank granting Institution
Asst. Professor	2024	Ninevah University
Lecturer	2021	Ninevah University
Asst. Lecturer	2016	Ninevah University

Practical experiences:

Tractical experien	CCS.		
Time]	period	Employar	Job Title
from	to	Employer	Job Title
2016	till now	Ninevah University	Teaching (Asst. Professor)
2022	2023	Ninevah University	Accreditation Division Manager
2021	2022	Ninevah University	Educational Laboratory Quality Division Manager
2021	2023	Ninevah University	Internal quality auditor
2020	till now	Ninevah University	Scientific paper reviewer
2015	2016	Oiltech Company	Field Engineer
2011	2013	Oilserv Company	Field Engineer

Scientific production (published/accepted for publication):

Research Title	Place of publication	Country of publication	Number	Vol	date of publication
Fick's Law Algorithm Based- Nonlinear Model Predictive Control of Twin Rotor MIMO System	Journal of Robotics and Control (JRC)	Indonesia	3	5	2024
Nonlinear Model Predictive Control- Based Collision Avoidance for Mobile Robot	Journal of Robotics and Control (JRC)	Indonesia	1	5	2024

Shared Control of a Robot Arm Using BCI and Computer Vision	Journal Européen des Systèmes Automatisés (JESA)	Canada	1	55	2022
Equilibrium Optimizer- Based Robust Sliding Mode Control of Magnetic Levitation System	Journal Européen des Systèmes Automatisés (JESA)	Canada	1	54	2021
Landmarks Exploration Algorithm for Mobile Robot Indoor Localization Using Vision Sensor	Journal of Engineering Science and Technology (JESTEC)	Malaysia	4	16	2021
Salp Swarm Algorithm- Based Nonlinear Robust Control of Magnetic Levitation System Using Feedback Linearization Approach	ACM International Conference Proceeding Series	Indonesia		ICECC 2020	2020
Quantitative design analysis of an electric scissor lift	American Scientific Research Journal for Engineering, Technology, and Sciences	Jordan	1	59	2019
Image De-noising using 2-D Circular-Support Wavelet Transform	American Scientific Research Journal for Engineering, Technology, and Sciences	Jordan	1	42	2018
Forward and inverse kinematic analysis and validation of the abb irb 140 industrial robot	Journal of Mechanical Engineering and Technology (JMET)	Malaysia	2	9	2017

Development of an omnidirectional mobile robot using embedded color vision system for ball following	American Scientific Research Journal for Engineering, Technology, and Sciences	Jordan	1	22	2016
Analysis, design, and implementation of an omnidirectional mobile robot platform	American Scientific Research Journal for Engineering, Technology, and Sciences	Jordan	1	22	2016

Conferences, scientific seminars and workshops in which I participated:

Research Title	Name of conference/seminar/workshop	Venue of the conference/seminar/workshop	Date
Salp Swarm Algorithm- Based Nonlinear Robust Control of Magnetic Levitation System Using Feedback Linearization Approach	International Conference on Electronics, Communications and Control Engineering (ICECC 2020)	Bali, Indonesia	2020
Interfacing LabVIEW with Arduino using visa and serial toolkit	Continuing education workshop	College of Electronics Engineering, Ninevah University	2022
Connecting Arduino to LabVIEW for	Continuing education workshop	College of Electronics Engineering, Ninevah University	2021

data acquisition application			
Programmable logic controllers (PLC) training with factory I/O	Continuing education workshop	College of Electronics Engineering, Ninevah University	2022
Design a Matlab based graphical user interface	Continuing education workshop	College of Electronics Engineering, Ninevah University	2022
Fuzzy logic controller using MATLAB toolbox and Simulink	Continuing education workshop	College of Electronics Engineering, Ninevah University	2021
Introduction to LabVIEW virtual instruments workbench	Continuing education workshop	College of Electronics Engineering, Ninevah University	2019
Real time data acquisition using LabVIEW interface for Arduino	Continuing education workshop	College of Electronics Engineering, Ninevah University	2019
Introduction to virtual robot experimentation platform (V-REP)	Continuing education workshop	College of Electronics Engineering, Ninevah University	2019
Introduction to PLC and industrial factory simulation	Continuing education workshop	College of Electronics Engineering, Ninevah University	2019
Graphical user Interface (GUI) design for robot control	Continuing education workshop	College of Electronics Engineering, Ninevah University	2019
Readiness of the quality	Internal quality audit program	Ninevah University	2023

management system in			
laboratories			
Good			
Laboratory	Quality workshop	Ninevah University	2021
Practice			
	symposium on support electrical		
	energy consumption and reduce	Ninevah University	2023
	emissions		
National			
standards for a			
Good	TOT	Ninevah University	2021
Laboratory			
Practice			
	symposium on combating	Ninevah University	2021
	extremism and extremism	Timevan Oniversity	2021
	Design Day Challenge	Ninevah University	2019
	Job fair	Ninevah University	2018
	Job fair	Ninevah University	2023

Courses(s) I have taught:

C (1: a)	Academic	University/
Course name (subject)	year	Institution
	-	Systems and Control
Process Control	2017-	Engineering
Flocess Collifor	2024	Department, Ninevah
		University
		Systems and Control
Computer Central Systems	2018-	Engineering
Computer Control Systems	2024	Department, Ninevah
		University
		Systems and Control
MATI AD Drogramming	2017-	Engineering
MATLAB Programming	2019	Department, Ninevah
		University
		Systems and Control
C++ Programming	2017-	Engineering
C++ Programming	2019	Department, Ninevah
		University
Systems Modelling	2023-	Systems and Control
Systems Modelling	2024	Engineering

		Department, Ninevah
		University
	2017-	Systems and Control
Process Control Lab	2017-	Engineering Department Ninevals
	2024	Department, Ninevah University
	2023-	Systems and Control
DSP Lab	2025	Engineering Department Ninevals
	2023	Department, Ninevah
		University Systems and Control
	2017-	Systems and Control
Signal and Systems Lab		Engineering
,	2018	Department, Ninevah
		University
	2015	Systems and Control
C++ LAB	2017-	Engineering
0 2.12	2019	Department, Ninevah
		University
		Systems and Control
Robotics Lab	2024-	Engineering
Roboties Lab	2025	Department, Ninevah
		University
		Systems and Control
MATLAB Lab	2017-	Engineering
WATEAD Eac	2019	Department, Ninevah
		University
2014	I WW T	+00

Supervising Bachelor's theses:

Title	Degree	Date
Analysis, Design, and Implementation of an Omnidirectional Robot	Bachelor	2017-2018
Indoor Localization based Omnidirectional Robot by using CMUcam5 cameras and CCs Beacons.	Bachelor	2018-2019
A Smart Control System of Home Appliances Using Brain Computer Interface (BCI)	Bachelor	2019-2020
Mind Guided Motion Control of A Prosthetics Arm using EEG Signals	Bachelor	2019-2020
PLC-Based Automatic Sorting process System via Factory I/O Industrial simulator	Bachelor	2020-2021
Design and Implementation of a PLC-Based Automatic Liquid Filling System	Bachelor	2020-2021
Boosting the automation of an elevator model system via adding PLC and HMI	Bachelor	2021-2022

Artificial Gorilla Troops Optimizer-Based Cross Coupled PID Controller for Twin Rotor MIMO System	Bachelor	2022-2023
Slime Mould Algorithm -Based PID Controller for Magnetic Levitation System	Bachelor	2022-2023
Design and Implementation of a Smart Pill Dispenser	Bachelor	2022-2023
Equilibrium Optimizer Algorithm-Based LQR Controller for Magnetic Levitation System	Bachelor	2023-2024
Crayfish Optimization Algorithm- Based PID Plus Feed Forward Controller for Coupled Tank System	Bachelor	2023-2024
Fick's Law Algorithm-Based PID Controller for Twin Rotor MIMO System	Bachelor	2023-2024
Flood algorithm-Based LQR with integral action for Coupled Tank System	Bachelor	2024-2025

